



Mission Planner 1.3.74 build 1.3.7563.27684 ArduCopter V4.0.7 (0bb18a15)

ARDUPILOT

COM15 115200

COM15-1-QUADROTOR

飞行数据 飞行计划 初始设置 配置/调试 模拟 帮助

飞行模式
地理围栏
基本调参
扩展调参
标准参数
高级参数
MAVftp
User Params
全部参数表
全部参数树
Planner

| 命令 | 值 | 单位 | 选项 | 描述 | Fav |
|------------------|-----|----|---|---|--------------------------|
| SERIAL2_BAUD | 115 | | 1:1200 2:2400 4:4800 9:9600 19:19200 38:38400 57:57600 111:111100 115:115200 256:256000 500:500000 921:921600 1500:1500000 | The baud rate of the Telem2 port. Most stm32-based boards can support rates of up to 1500. If you setup a rate you cannot support and then can't connect to your board you should load a firmware from a different vehicle type. That will reset all your parameters to defaults. | <input type="checkbox"/> |
| SERIAL2_PROTOCOL | 20 | | 1:None 1:MAVLink1 2:MAVLink2 3:Frsky D 4:Frsky SPort 5:GPS 7:Alexmos Gimbal Serial 8:StoRM32 Gimbal Serial 9:Rangefinder 10:FrSky SPort Passthrough (Open TX) 11:Lidar360 13:Beacon 14:Volz servo out 15:SBUS servo out 16:ESC Telemetry 17:Devo Telemetry 18:OpticalFlow 19:RobotisServo 20:NMEA Output 21:WindVane 22:SLCAN 23:RCIN | Control what protocol to use on the Telem2 port. Note that the Frsky options require external converter hardware. See the wiki for details. | <input type="checkbox"/> |

所有单位都会以原始格式储存, 不会被压缩

加载参数
重置为默认值
telem2
Modified